

Simplifying systems of differential equations

The case of the Sunrise graph

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partly based on collaboration with *E. Remiddi*

[\[arXiv:1311.3342\]](#), [\[arXiv:1509.03330\]](#)

Introduction

1. Our understanding of Standard model is based on perturbative expansions in **Feynman Diagrams**
2. Feynman Diagrams can be expressed as collection of **Feynman Integrals**
3. **Analytical** or **numerical** calculation of Feynman Integrals of increasing complexity is of crucial importance for precise and reliable prediction to be compared with most recent measurements.



One of the most powerful techniques for computing Feynman Integrals is the
Differential equations method

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The two-loop massive sunrise graph

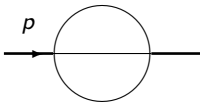
$$\mathcal{I}(n_1, n_2, n_3, n_4, n_5) = \text{Diagram}$$

$$= \int \mathcal{D}^d k \mathcal{D}^d l \frac{(k \cdot p)^{n_4} (l \cdot p)^{n_5}}{(k^2 - m_1^2)^{n_1} (l^2 - m_2^2)^{n_2} ((k - l - p)^2 - m_3^2)^{n_3}}$$

$$= \int \mathcal{D}^d k \mathcal{D}^d l \frac{(k \cdot p)^{n_4} (l \cdot p)^{n_5}}{D_1^{n_1} D_2^{n_2} D_3^{n_3}}$$

How do we compute all these integrals?

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 \end{aligned}$$


How do we compute all these integrals?

Standard way to proceed

1. Use Integration-by-parts id.s (IBPs) to reduce them to **Master Integrals**
2. Use IBPs to derive **differential equations** (DE) satisfied by the MIs.
3. Try to solve these differential equations.

One finds:

- a) Sunrise graph reduced to **4 MIs**
- b) In general 4 **coupled** differential equations.

Different **choice** of the basis can **simplify** system of DE!

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How does this work for the Sunrise?

Choice 1

$$S_1 = \int \frac{\mathfrak{D}^d k \mathfrak{D}^d l}{D_1 D_2 D_3}, \quad S_2 = \int \frac{\mathfrak{D}^d k \mathfrak{D}^d l}{D_1^2 D_2 D_3}, \quad S_3 = \int \frac{\mathfrak{D}^d k \mathfrak{D}^d l}{D_1 D_2^2 D_3}, \quad S_4 = \int \frac{\mathfrak{D}^d k \mathfrak{D}^d l}{D_1 D_2 D_3^2}$$

→ 4 coupled DE in $d = 4$ and in $d = 2$ (and in any even number of dimensions...).

Choice 2

$$\begin{aligned} \tilde{S}_1 &= \int \mathfrak{D}^d k \mathfrak{D}^d l \frac{1}{D_1 D_2 D_3}, & \tilde{S}_2 &= \int \mathfrak{D}^d k \mathfrak{D}^d l \frac{1}{D_1^2 D_2 D_3}, \\ \tilde{S}_3 &= \int \mathfrak{D}^d k \mathfrak{D}^d l \frac{k \cdot p}{D_1 D_2 D_3}, & \tilde{S}_4 &= \int \mathfrak{D}^d k \mathfrak{D}^d l \frac{l \cdot p}{D_1 D_2 D_3} \end{aligned}$$

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- a) Result above found by **trial and error**.
→ What is the **irreducible number of coupled masters**?

- b) Initially answer through **Schouten Identities** in $d = 2$ dimensions
[Remiddi, Tancredi '13]

- c) We will present here a generalisation of the method above.
Easier to apply and more powerful



Study IBPs in **fixed number of dimensions**!

Fixing the values of d to an integer number in the IBPs can make the MIs degenerate → some of the MIs can become **linearly dependent** from the others!

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Imagine to produce IBPs for Sunrise graph with three different masses and, before solving them, **fix $d = 2$** .

- a) This is equivalent to studying the IBPs as a *Laurent series* in $(d - 2)$
Feynman Integrals are in general **divergent** as $d \rightarrow n \in \mathbb{N}$

- b) Upon solving the IBPs in $d = 2$ we find two new relations. This implies that in $d = 2$ there the MIs degenerate and only 2 Masters are **linearly independent!**

$$m_2^2 P(s, m_1^2, m_2^2, m_3^2) S_3(2; s) = (m_1^2 - m_2^2)(m_1^2 + m_2^2 - m_3^2 - s) S_1(2; s) \\ + m_1^2 (m_1^4 - 3m_2^4 + 2m_1^2(m_2^2 - m_3^2 - s) + (m_3^2 - s)^2 + 2m_2^2(m_3^2 + s)) S_2(2; s)$$

$$m_3^2 P(s, m_1^2, m_2^2, m_3^2) S_4(2; s) = (m_1^2 - m_3^2)(m_1^2 - m_2^2 + m_3^2 - s) S_1(2; s) \\ + m_1^2 (m_1^4 + m_2^4 - 3m_3^4 + 2m_2^2(m_3^2 - s) + 2m_3^2 s + p^4 - 2m_1^2(m_2^2 - m_3^2 + s)) S_2(2; s),$$

where we defined the polynomial

$$P(s, m_1^2, m_2^2, m_3^2) = (-3m_1^4 + m_2^4 + (m_3^2 - s)^2 - 2m_2^2(m_3^2 + s) + 2m_1^2(m_2^2 + m_3^2 + s)).$$

Using this piece of information we can define a new basis of MIs in **d dimensions!**

$$S_1 = S_1(d; s), \quad S_2 = S_2(d; s) \quad \text{unchanged}$$

$$\begin{aligned} Z_3 = & m_2^2 P(s, m_1^2, m_2^2, m_3^2) S_3(d; s) - (m_1^2 - m_2^2)(m_1^2 + m_2^2 - m_3^2 - s) S_1(d; s) \\ & - m_1^2 (m_1^4 - 3m_2^4 + 2m_1^2(m_2^2 - m_3^2 - s) + (m_3^2 - s)^2 + 2m_2^2(m_3^2 + s)) S_2(d; s) \end{aligned}$$

$$\begin{aligned} Z_4 = & m_3^2 P(s, m_1^2, m_2^2, m_3^2) S_4(d; s) - (m_1^2 - m_3^2)(m_1^2 - m_2^2 + m_3^2 - s) S_1(d; s) \\ & - m_1^2 (m_1^4 + m_2^4 - 3m_3^4 + 2m_2^2(m_3^2 - s) + 2m_3^2 s + p^4 - 2m_1^2(m_2^2 - m_3^2 + s)) S_2(d; s), \end{aligned}$$

Such that by definition

$$Z_3 \approx Z_4 \approx \mathcal{O}((d-2))$$

Differential equations for the new basis assume **block form** as $d \rightarrow 2$

$$\frac{d}{d p^2} \begin{pmatrix} S_1 \\ S_2 \\ Z_3 \\ Z_4 \end{pmatrix} = \begin{pmatrix} c_{11} & c_{12} & c_{13} & c_{14} \\ c_{21} & c_{22} & c_{23} & c_{24} \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} S \\ S_1 \\ Z_2 \\ Z_3 \end{pmatrix} + \mathcal{O}((d-2))$$

The two new master integrals are **completely decoupled** in the limit $d \rightarrow 2$!

Order by order in $(d-2)$ we can derive a **second order differential equation** satisfied by $S(d; p^2)$. [see Weinzierl et al., '11]

⇓

Solution of second order differential equation in terms of
Elliptic Polylogarithms [see Luise Adams' talk]

The method can be easily generalized

- a) In **different numbers of dimensions** $d = n \in \mathbb{N}$
- b) For any **other topology** irrespective of number of loops or masses!

As a (*natural*) extension **the three-loop banana graph**

$$I_4(d; n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9) = \text{---} \rightarrow \begin{array}{c} p \\ \circlearrowleft \\ \circlearrowright \\ \circlearrowleft \\ \circlearrowright \end{array} \text{---}$$

$$= \int \mathfrak{D}^d k_1 \mathfrak{D}^d k_2 \mathfrak{D}^d k_3 \frac{(k_1 \cdot p)^{n_5} (k_2 \cdot p)^{n_6} (k_3 \cdot p)^{n_7} (k_1 \cdot k_2)^{n_8} (k_1 \cdot k_3)^{n_9}}{(k_1^2 - m_1^2)^{n_1} (k_2^2 - m_2^2)^{n_2} (k_3^2 - m_3^2)^{n_3} ((k_1 + k_2 + k_3 - p)^2 - m_4^2)^{n_4}}$$

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The case of **all equal masses**

All masses equal $m_4 = m_3 = m_2 = m_1 = m \rightarrow 3$ MIs in d dimensions

$$\mathcal{I}_1(d; s) = h_1(d; 1, 1, 1, 1, 0, 0, 0, 0, 0), \quad \mathcal{I}_2(d; s) = h_1(d; 2, 1, 1, 1, 0, 0, 0, 0, 0),$$

$$\mathcal{I}_3(d; s) = h_1(d; 3, 1, 1, 1, 0, 0, 0, 0, 0).$$

They **remain independent if $d = 2$** \rightarrow The scalar master integrals fulfil a **third-order differential equation!**

$$D_d^{(3)} \mathcal{I}_1(d; s) = 0,$$

$$D_d^{(3)} = \frac{d^3}{d s^3} + \frac{3(64m^4 + 10(d-5)m^2s - (d-4)s^2)}{s(s-4m^2)(s-16m^2)} \frac{d^2}{d s^2}$$

$$+ \frac{(d-4)(11d-36)s^2 - 64(d-4)d m^4 - 4(216 + d(7d-88))m^2 s}{4s^2(s-4m^2)(s-16m^2)} \frac{d}{d s}$$

$$+ \frac{(3-d)(3d-8)(2(d+2)m^2 + (d-4)s)}{4s^2(s-4m^2)(s-16m^2)}$$

The case of **two different masses** - two different configurations

$$I_2^A(d; n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9) = I_4(d; n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9) \Big|_{m_3=m_2=m_1=m_a, m_4=m_b}$$

$$I_2^B(d; n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9) = I_4(d; n_1, n_2, n_3, n_4, n_5, n_6, n_7, n_8, n_9) \Big|_{m_2=m_1=m_a, m_4=m_3=m_b}$$

A) In configuration A **5 independent** MIs in d dimensions

$$\mathcal{I}_1^A(d; s) = I_2^A(d; 1, 1, 1, 1, 0, 0, 0, 0, 0), \quad \mathcal{I}_2^A(d; s) = I_2^A(d; 2, 1, 1, 1, 0, 0, 0, 0, 0),$$

$$\mathcal{I}_3^A(d; s) = I_2^A(d; 1, 1, 1, 2, 0, 0, 0, 0, 0), \quad \mathcal{I}_4^A(d; s) = I_2^A(d; 3, 1, 1, 1, 0, 0, 0, 0, 0),$$

$$\mathcal{I}_5^A(d; s) = I_2^A(d; 2, 2, 1, 1, 0, 0, 0, 0, 0)$$

B) In configuration B **6 independent** MIs in d dimensions

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Simplifying the system of differential equations in $d = 2$

A) Solving IBPs in $d = 2$ we find that **4 MIs** remain independent

$$\begin{aligned}
 m_a^2(s - 5m_a^2 + m_b^2) \mathcal{I}_5^A(2; s) = & \\
 + \frac{3m_a^2 + m_b^2 - s}{12 m_a^2} \mathcal{I}_1^A(2; s) + \frac{51m_a^4 + (m_b^2 - s)^2 - 6m_a^2(m_b^2 + 2s)}{12 m_a^2} \mathcal{I}_2^A(2; s) & \\
 + \frac{m_b^2(m_b^2 - s)}{6 m_a^2} \mathcal{I}_3^A(2; s) + \frac{21m_a^4 + (m_b^2 - s)^2 - 6m_a^2(m_b^2 + s)}{6} \mathcal{I}_4^A(2; s). &
 \end{aligned}$$

B) Similarly we find here **two relations** such that again only 4 MIs remain independent

$$\mathcal{I}_5^B(s; 2) = a_1 \mathcal{I}_1(2; s) + a_2 \mathcal{I}_2(2, s) + a_3 \mathcal{I}_3(2, s) + a_4 \mathcal{I}_4(2, s)$$

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As for the two-loop sunrise, these relations can be used to decouple 1 (2) MIs from the system of differential equations.

4 differential equations remain **coupled**, corresponding to a **fourth-order differential equation** for the scalar amplitude.

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B) Similarly we find here **two relations** such that again only 4 MIs remain independent

$$\mathcal{I}_5^B(s; 2) = a_1 \mathcal{I}_1(2; s) + a_2 \mathcal{I}_2(2, s) + a_3 \mathcal{I}_3(2, s) + a_4 \mathcal{I}_4(2, s)$$

$$\mathcal{I}_6^B(s; 2) = b_1 \mathcal{I}_1(2; s) + b_2 \mathcal{I}_2(2, s) + b_3 \mathcal{I}_3(2, s) + b_4 \mathcal{I}_4(2, s)$$

As for the two-loop sunrise, these relations can be used to decouple 1 (2) MIs from the system of differential equations.

4 differential equations remain **coupled**, corresponding to a **fourth-order differential equation** for the scalar amplitude.

Simplifying the system of differential equations in $d = 2$

A) Solving IBPs in $d = 2$ we find that **4 MIs** remain independent

$$\begin{aligned}
 m_a^2(s - 5m_a^2 + m_b^2) \mathcal{I}_5^A(2; s) = & \\
 + \frac{3m_a^2 + m_b^2 - s}{12 m_a^2} \mathcal{I}_1^A(2; s) + \frac{51m_a^4 + (m_b^2 - s)^2 - 6m_a^2(m_b^2 + 2s)}{12 m_a^2} \mathcal{I}_2^A(2; s) & \\
 + \frac{m_b^2(m_b^2 - s)}{6 m_a^2} \mathcal{I}_3^A(2; s) + \frac{21m_a^4 + (m_b^2 - s)^2 - 6m_a^2(m_b^2 + s)}{6} \mathcal{I}_4^A(2; s). &
 \end{aligned}$$

B) Similarly we find here **two relations** such that again only 4 MIs remain independent

$$\mathcal{I}_5^B(s; 2) = a_1 \mathcal{I}_1(2; s) + a_2 \mathcal{I}_2(2, s) + a_3 \mathcal{I}_3(2, s) + a_4 \mathcal{I}_4(2, s)$$

$$\mathcal{I}_6^B(s; 2) = b_1 \mathcal{I}_1(2; s) + b_2 \mathcal{I}_2(2, s) + b_3 \mathcal{I}_3(2, s) + b_4 \mathcal{I}_4(2, s)$$

As for the two-loop sunrise, these relations can be used to decouple 1 (2) MIs from the system of differential equations.

4 differential equations remain **coupled**, corresponding to a **fourth-order differential equation** for the scalar amplitude.

The **general case** with 4 different masses

In the most general case one finds **11 different master integrals** in d dimensions

$$\begin{aligned}
 \mathcal{I}_1(d; s) &= I_4(d; 1, 1, 1, 1, 0, 0, 0, 0, 0), & \mathcal{I}_2(d; s) &= I_4(d; 2, 1, 1, 1, 0, 0, 0, 0, 0), \\
 \mathcal{I}_3(d; s) &= I_4(d; 1, 2, 1, 1, 0, 0, 0, 0, 0), & \mathcal{I}_4(d; s) &= I_4(d; 1, 1, 2, 1, 0, 0, 0, 0, 0), \\
 \mathcal{I}_5(d; s) &= I_4(d; 1, 1, 1, 2, 0, 0, 0, 0, 0), & \mathcal{I}_6(d; s) &= I_4(d; 3, 1, 1, 1, 0, 0, 0, 0, 0) \\
 \mathcal{I}_7(d; s) &= I_4(d; 2, 2, 1, 1, 0, 0, 0, 0, 0), & \mathcal{I}_8(d; s) &= I_4(d; 2, 1, 2, 1, 0, 0, 0, 0, 0) \\
 \mathcal{I}_9(d; s) &= I_4(d; 2, 1, 1, 2, 0, 0, 0, 0, 0), & \mathcal{I}_{10}(d; s) &= I_4(d; 1, 2, 2, 1, 0, 0, 0, 0, 0) \\
 \mathcal{I}_{11}(d; s) &= I_4(d; 1, 2, 1, 2, 0, 0, 0, 0, 0).
 \end{aligned}$$

Repeating the exercise of solving the IBPs in $d = 2$ we find **5 independent relations** such that **6 master integrals** remain independent!

→ corresponds to a *sixth-order differential equation for the scalar amplitude*

Conclusions

- a) Differential equations are one of the most important tools for calculation of Feynman integrals
- b) For complicated Feynman graph one is often faced with **large systems of coupled differential equations**
- c) Coupled differential equations can be simplified in the limit $d \rightarrow n \in \mathbb{N}$ by decoupling some of the equations in that limit.
- d) Information needed for the decoupling can be found **studying the IBPs** in the limit $d \rightarrow n \in \mathbb{N}$!

Given a topology, what is the **irreducible** number of **coupled master integrals**?

Thanks!